

Robotic Sensor Networks

Why robots?

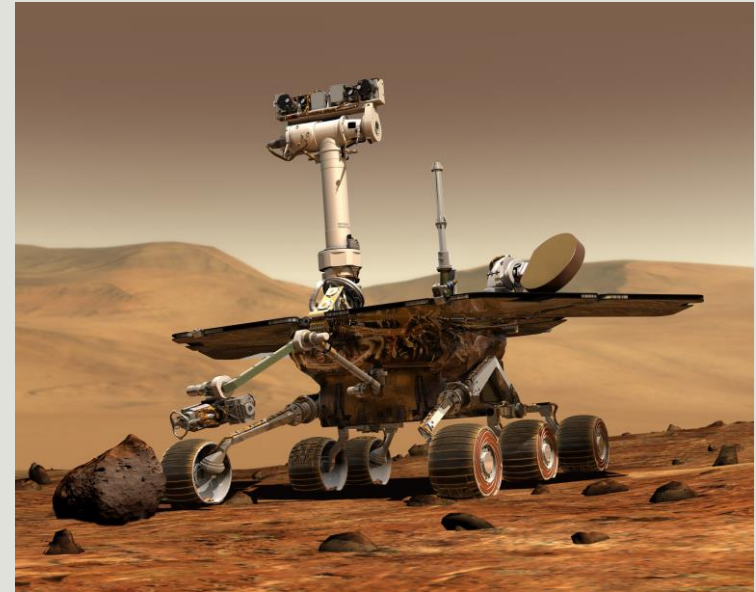
I would like to do _____,

but I don't have enough _____.

Why robots?

I would like to do geology on Mars ,

but I don't have enough ways to get home .



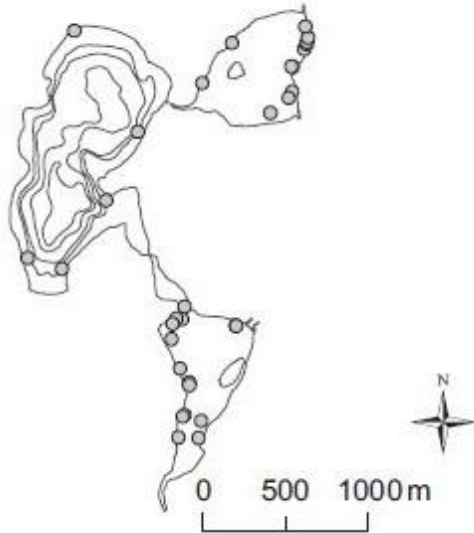
Invasive Species Monitoring



Once located, an aggregation of invasive fish can be effectively and safely removed

Invasive Species Monitoring

26 April 2010



13 January 2010



Aggregations!



Aggregations occur unpredictably, requiring constant vigilance.

Why robots?

I would like to do Invasive Species Monitoring,

but I don't have enough of these guys .

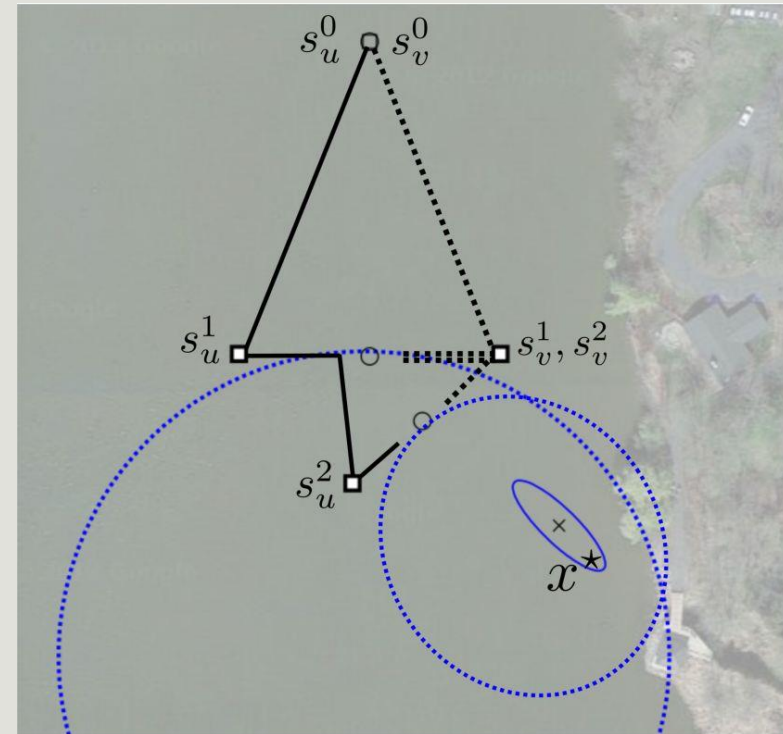
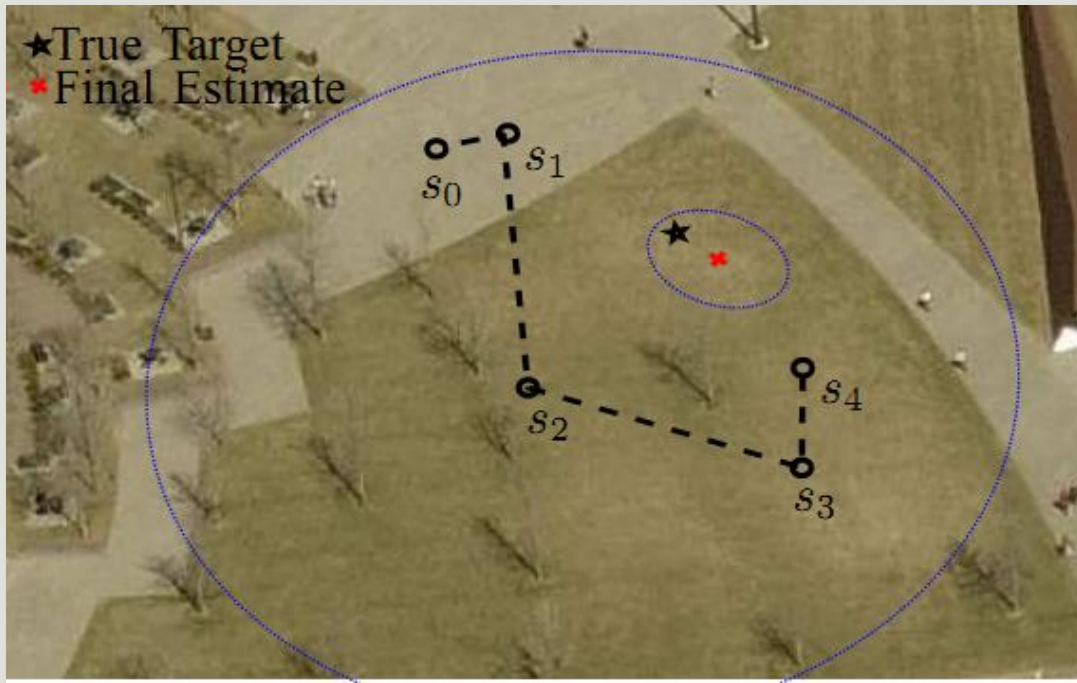


How we solve

1. Abstract the problem *using a useful mathematical formulation*
2. Solve the abstracted problem *and provide guarantees of quality*
3. Verify the abstraction *in the field, extensively*

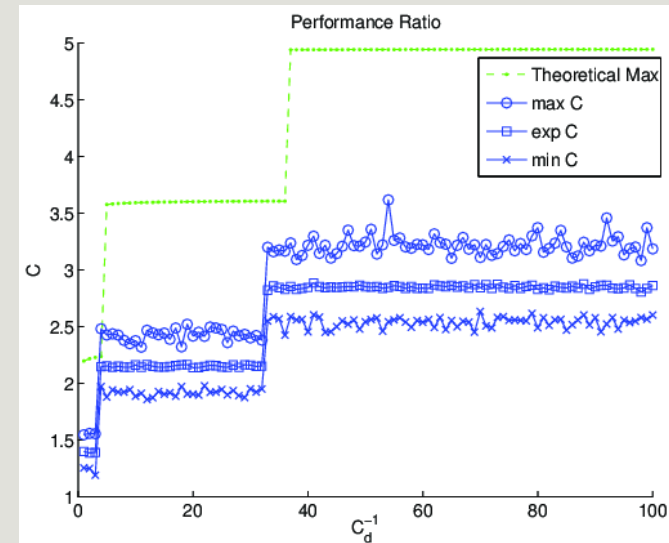
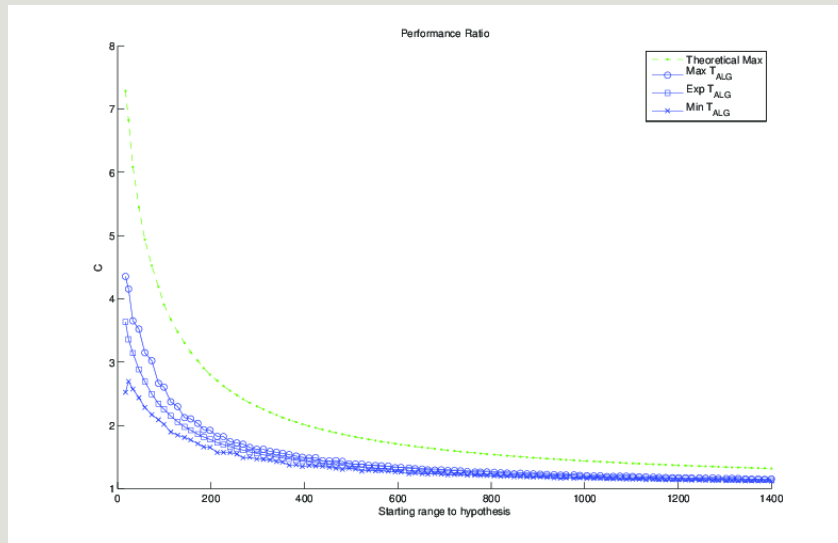
Example Solution

1. Novel Active Measurement Strategy to locate stationary fish (i.e., in an aggregation)



Example Solution

1. Novel Active Measurement Strategy
2. Provided the first lower and upper bound on time to localize



Example Solution

1. Novel Active Measurement Strategy
2. Provided the first lower and upper bound on time to localize
3. Documented three years of field experiments ...







Thanks!

